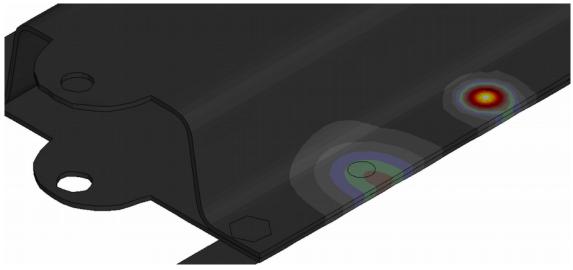


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# Digital distortion compensation solution for BIW assemblies by reverse simulation of joining process influences



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#### We quest for perfectness ...

- In manufactoring of BIW process steps follow next process steps
- No step is perfect
  - Stamping  $\rightarrow$  imperfect single part
  - Clamping  $\rightarrow$  more imperfections by clamp closing
  - Welding  $\rightarrow$  followed by deviation of weld shrinkage
- But the final assembly shall exact fit the target geometry

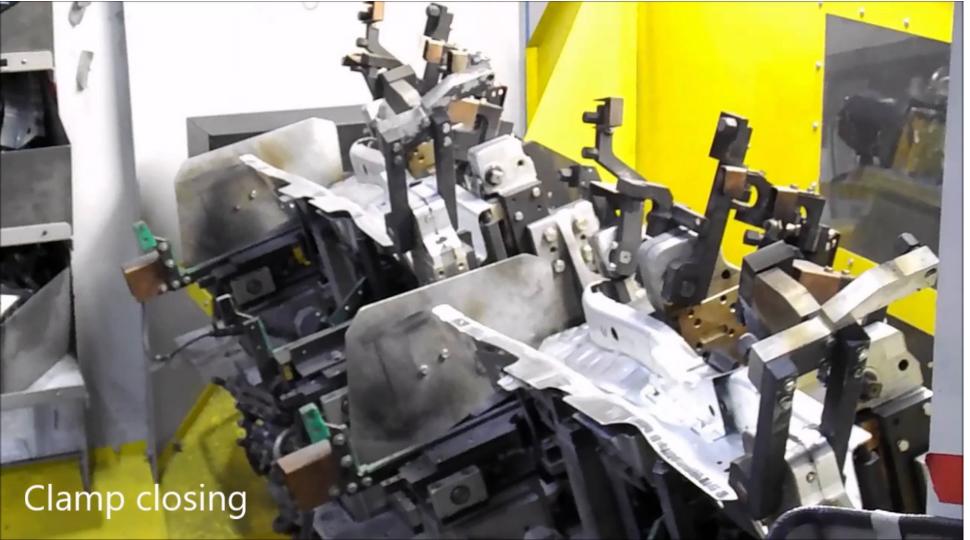
... with engineering we shall succeed

The hat-profile is related to BIW frame structure,

thus we will investigate our engineering in this type of structure



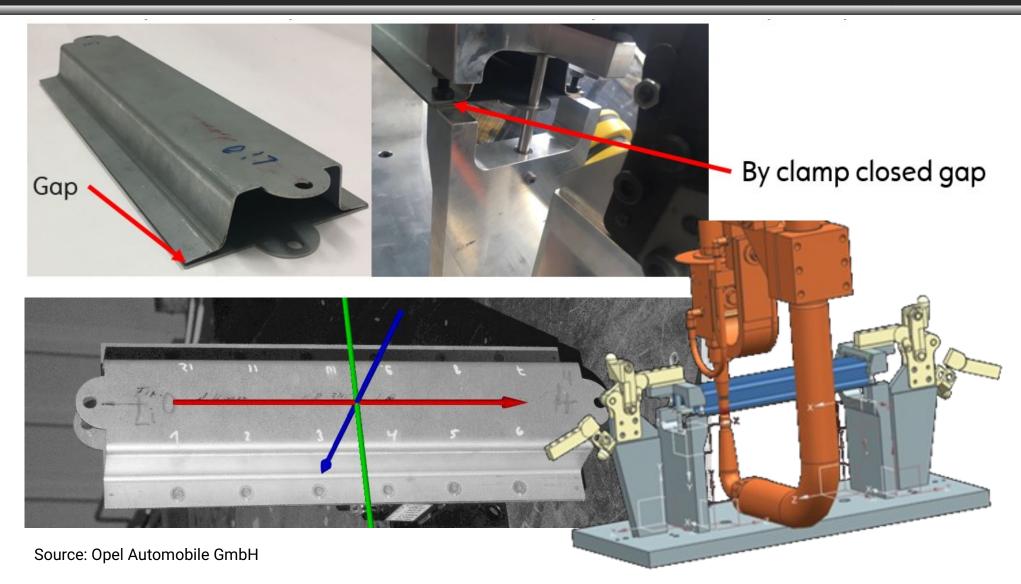
# **Clamping and Welding in Reality**



Source: Opel Automobile GmbH

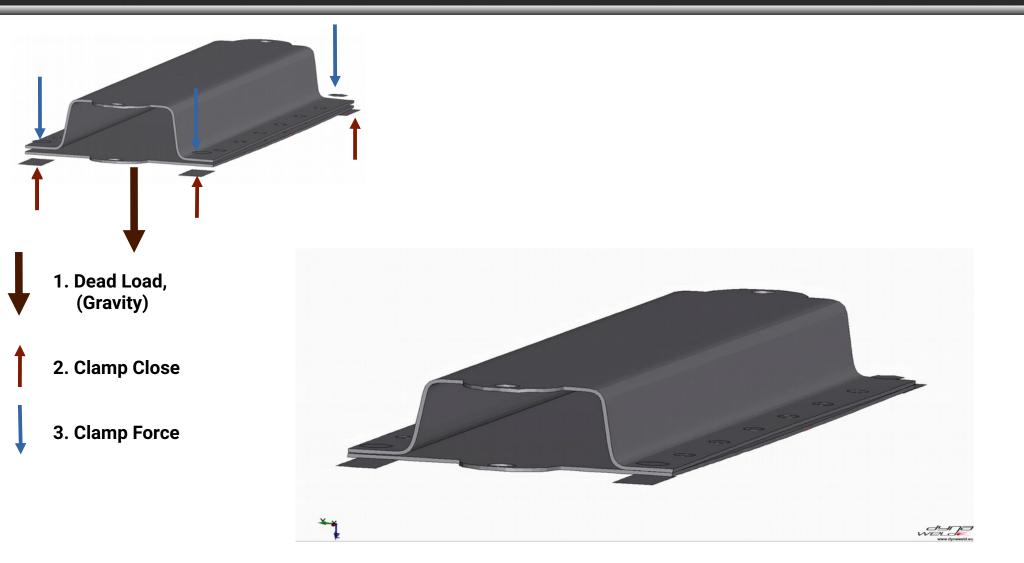


# Clamping and Welding of Imperfect Single Parts





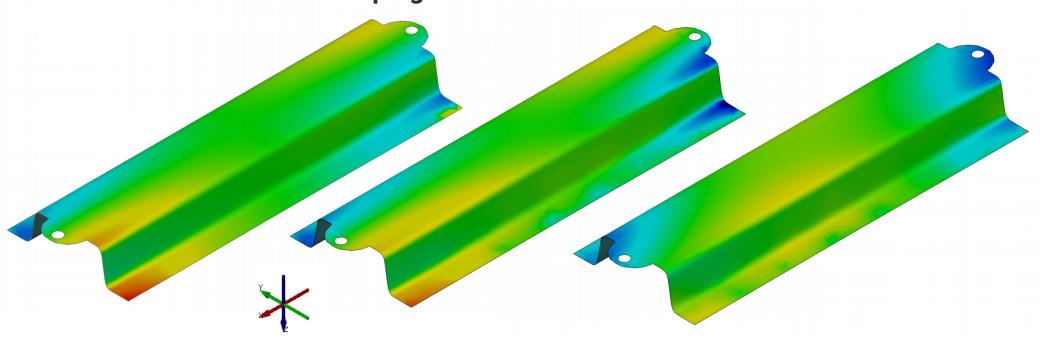
Clamping





# Deviation due to Clamping, Welding, Clamp Release

Deviation of the surfaces to the initial state after stamping which is the state before clamping

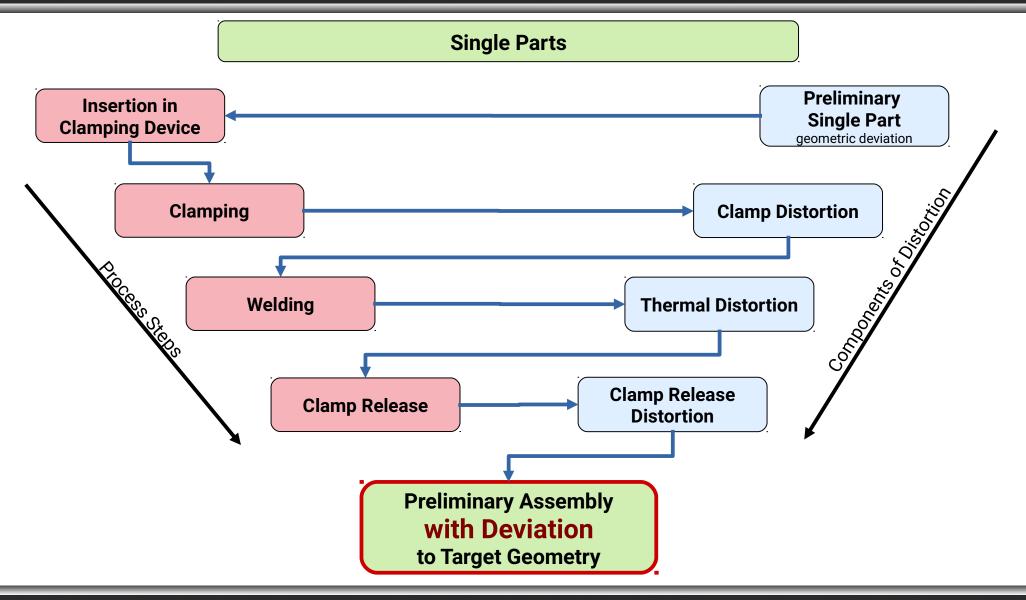


**After Clamping** 

After Welding Before Clamp Release After Clamp Release and Complete Cooling



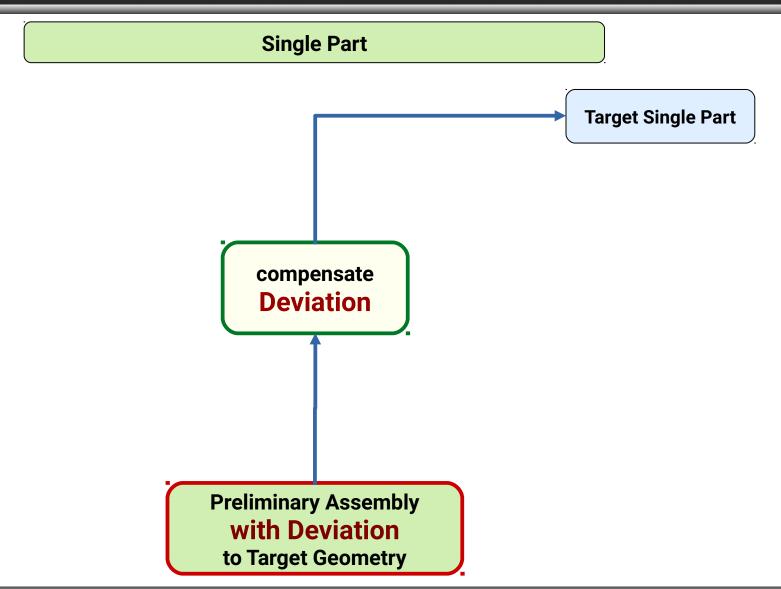
#### **Assembly** Real Sequence of Manufacturing - Forward View





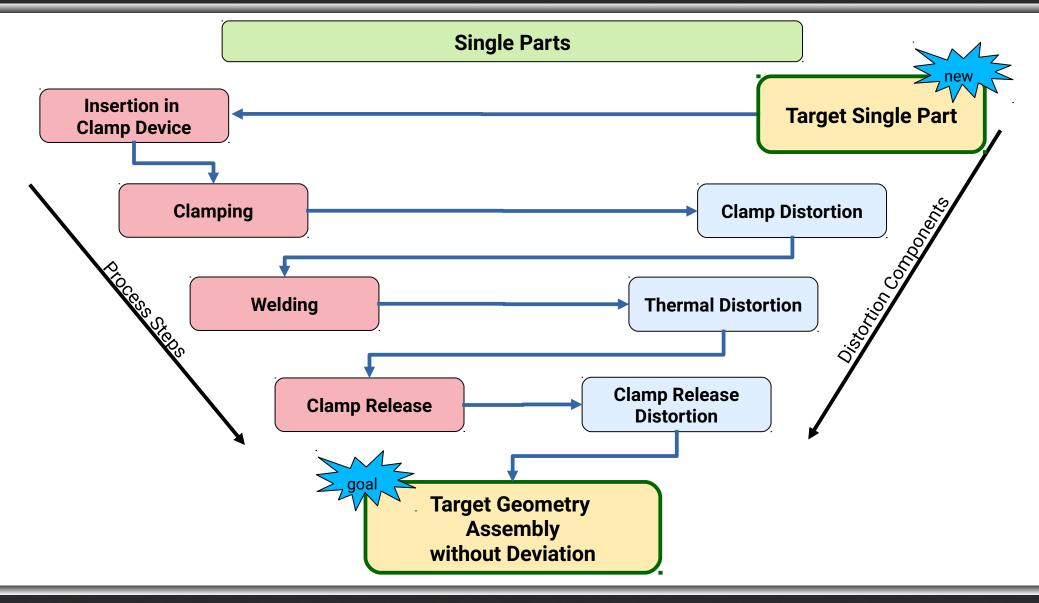
#### **Motivation**

**Compensation by Track Back of the Deviation of Geometry** 





#### **Assembly** Manufacturing - Forward View with Compensation



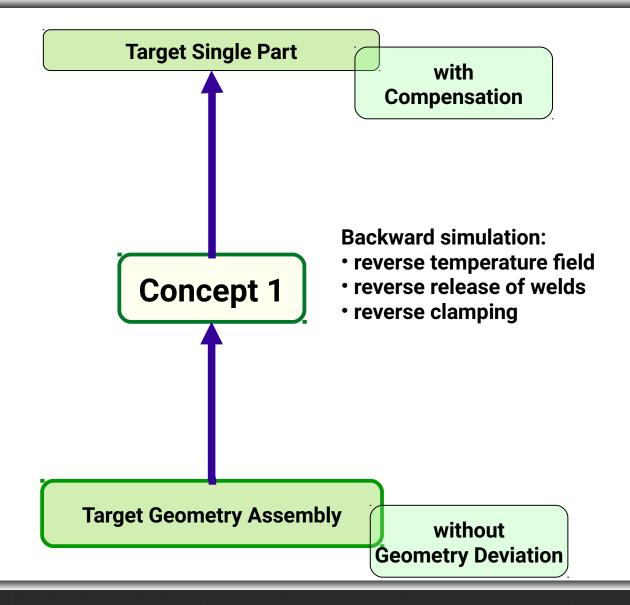


# **Concept 1**

Thermal Compensation Backward Simulation of Weld Distortion



## Concept 1 Thermal Compensation





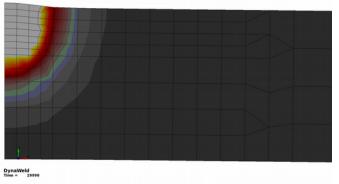
#### **Thermal Distortion** Reverse of Temperature Field

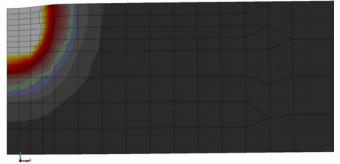
# **Reverse of Temperature Field**

DynaWeld enables the backward simulation of a prior forward simulated

Temperature field.

This method consideres also the reverse heat coduction from surface to environment.



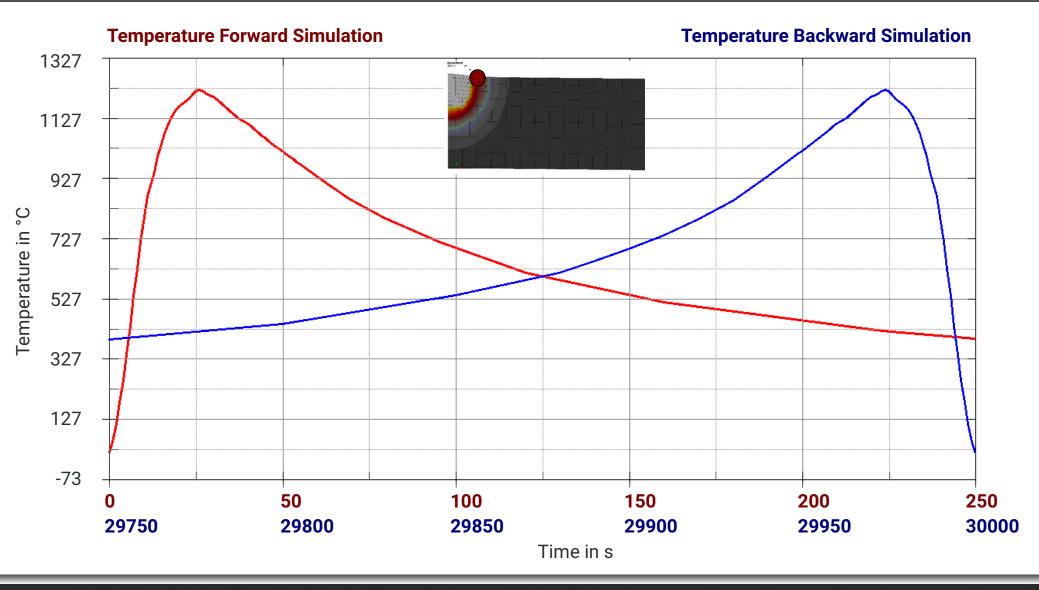








#### **Thermal Distortion** Reverse of Temperature Field





### **Basis (Start):**

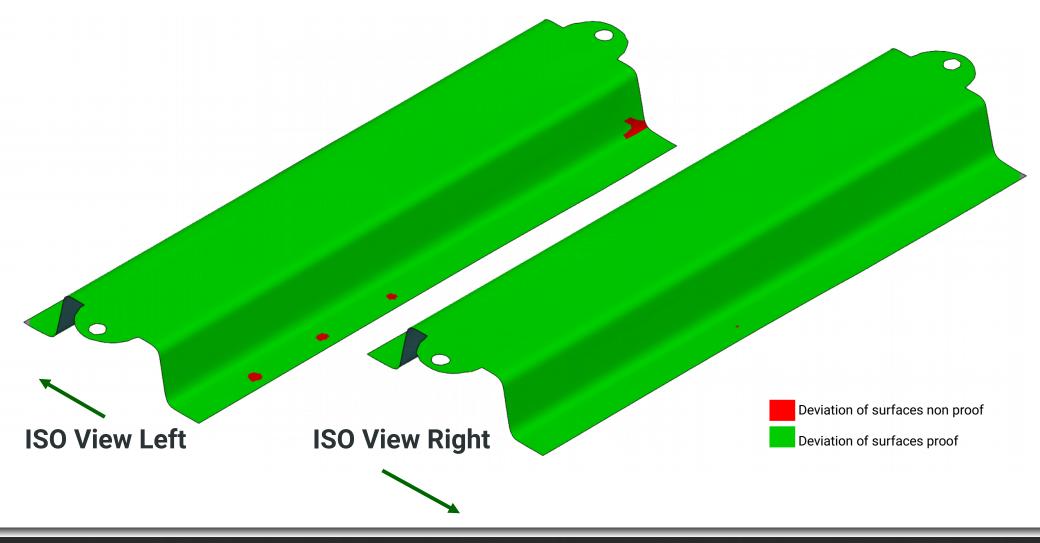
- •Measured real geometry of the assembly: Geometry A.
- Simulation:
- •Backward simulation. Initial state is Geometry A.
- **Result of Simulation:**
- •Calculated initial geometry of single part,
- •this is the state before clamping and welding
- •this is the imperfect geometry of the single part: Geometry B

# Proof:

•The measured geometry of single part before clamping and welding, Geometry C, shall fit best the simulated geometry B to proof the method



#### **Deviation of the surfaces Geometry B and Geometry C**



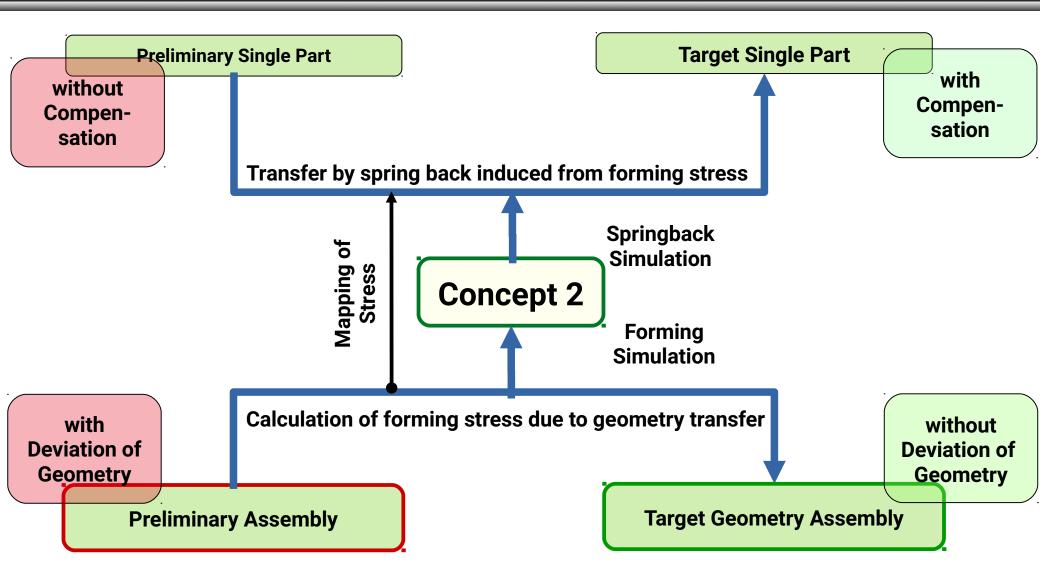


# Concept 2

Transfer Simulation with Transfer of Forming Stress

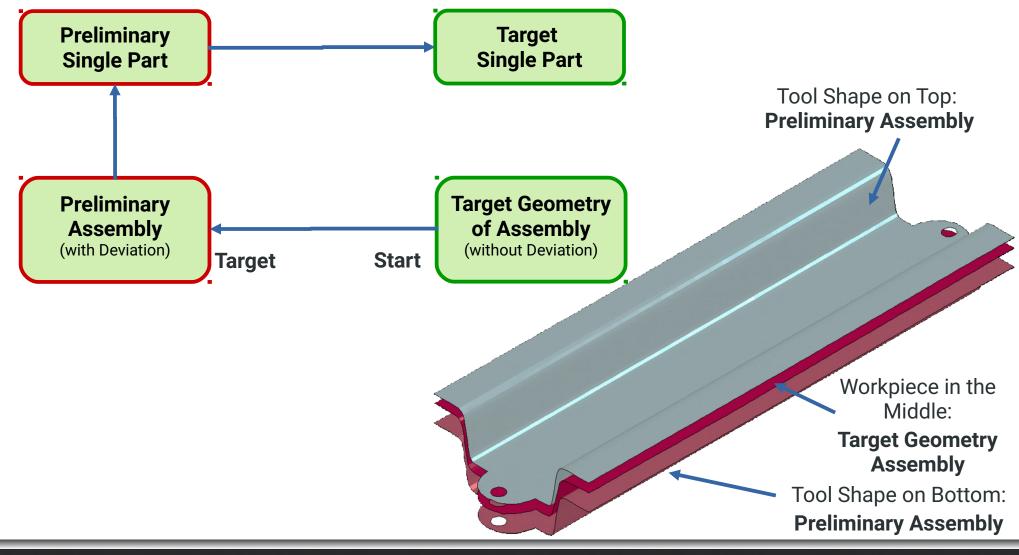


# Concept 2 Compensation via Transfer of Forming Stress





## Compensation by Transfer of Forming Stress





## **Basis (Start):**

- •CAD geometry of the single part: Geometry D.
- First Simulation:
- •Calculate forming stresses
- •from measured geometry of single part before clamping and welding (Geometry C)
  •to measured geometry of preliminary assembly (Geometry E)

# Second Simulation:

- •Initial state is geometry D
- Mapping forming stresses
- •Simulation of spring back due to mapped forming stresses
- **Result of Simulation:**
- •Calculated initial geometry of single part before clamping and welding: Geometry B **Proof:**
- •The measured geometry of single part before clamping and welding, Geometry C shall fit best the simulated geometry B to proof the method.



**Deviation of the surfaces Geometry B and Geometry C** 



Deviation of surfaces non proof
Deviation of surfaces proof

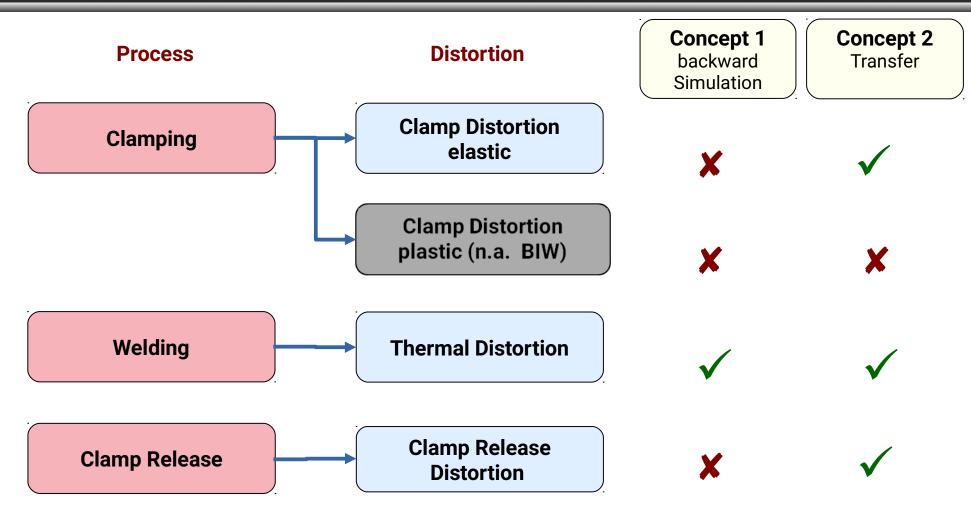


# Comparison

Application Field and Limitation of the Methods



# **Application Fields**



Plastic deformation, which may occur at clamping, can not be covered. Concept 2 is applicable if the clamping remains only with elastic response of the structure.



# **Possible Application in BIW**

Front Frame



### Manufacturing design of a new front frame

Applicable in an early state of the design far before anything is manufacured in reality. Manufacturing reviewed in the engineering department only.

- •Imperfect geometry of single part obtained by forming simulation
- •Forward simulation of assembly with imperfect prelimary single parts
  - Analysis of distortion
  - Calculation of deviation from target geometry
  - Detection of parts with major influence on deviation from target geometry
- •Design of compensation
  - design of new geometry for mayor single parts with compensation
- Proof of choosen manufacturing design
  - Forward analysis again
  - Single parts with compensation
  - Goal: Assembly now fits the target geometry



Benefit

# Define compensation in design phase - no need of prototype test



Source: Opel Automobile GmbH



### Manufacturing design of a new front frame

Applicable in shop floor during the setup of the production line

- •Imperfect geometry of single part obtained by measurement (3D scan)
- •Geometry of preliminary assembly obtained by measurement (3D scan)
- Design of compensation
  - design of new geometry for mayor single parts with compensation
- •Proof of choosen manufacturing design
  - Forward analysis
  - Single parts with compensation
  - Goal: Assembly now fits the target geometry



Benefit

# Reduce number of many try out loops to one single loop



Source: Opel Automobile GmbH



# Thanks for your Attention!

